THALES

MCTS-based Automated Negotiation Agent

Cédric Buron¹, Zahia Guessoum^{2,3}, Sylvain Ductor⁴

¹Thales Research & Technology,

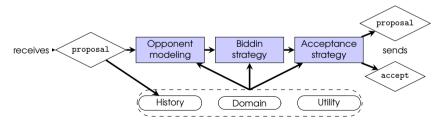
²LIP6, Sorbonne Université, ³ CReSTIC, Université de Reims Champagne-Ardennes

⁴Universidade Estadual do Ceará cedric.buron@thalesgroup.com

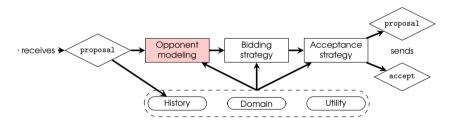
29/10/2019



- Goal: an agent able to negotiate when:
 - > the protocol is bargaining with or without deadline
 - > goods are multi-issues, categorical and/or continuous
- Example: invoice trading for supply chain
- BOA [1]: Bidding Strategy, Opponent modeling & Acceptance strategy









Gaussian Process regression (extension of multivariate Gaussian) [8]

Let (x_i, y_i) . Suppose:

$$\begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \sim \mathcal{N}(\mathbf{0}, K(x_i))$$

with K, covariance matrix representing the proximity of the negotiation turns with each others, according to a covariance function k:

$$K(x_i) = (k_{jk}) = (k(x_j, x_k))$$

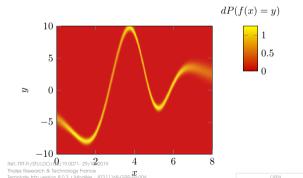
Then, we predict for turn x_* :

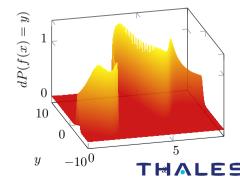
$$\begin{pmatrix} y_1 \\ \vdots \\ y_n \\ y_* \end{pmatrix} \sim \mathcal{N}(\mathbf{0}, \mathcal{K}(x_l, x_*))$$



$$\begin{cases} \bar{y_*} = K_* K^{-1} \mathbf{y} \\ \sigma_* = \text{var}(y_*) = K_{**} - K_* K^{-1} K_*^{\top} \end{cases}$$

where $K_* = (k(x_*, x_1), \dots, k(x_*, x_n))$ et $K_{**} = k(x_*, x_*)$.

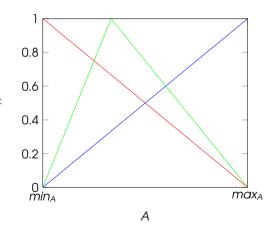




Bayesian learning hypothesis:

- \triangleright triangular functions t_i for each issue
- ⇒ a rank τ_i for the issue $i \to \text{weight}$ $w_i = 2 \frac{\tau_i}{n \cdot (n+1)}$
- For an offer (x_1, \ldots, x_n) , prediction:

$$h(b) = \sum_{1 \le i \le p} w_i \cdot t_i(x_i)$$



Réf.:TRT-Fr/STI/LDO/CB/19,0071- 29/10/2019 Thales Research & Technology France Template trtp version 8,0,3 / Modèle : 87211168-GRP-FR-004

EN .

THALES

Concessions supposed monotonous and approx. regular

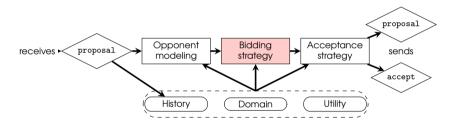
▶ (≈ u^0 : $b \mapsto 1 - \alpha_u \cdot round(b)$, whith α_u a parameter)

$$P(b|h_{j}) = \frac{1}{\sigma \cdot \sqrt{2\pi}} \cdot e^{-\frac{\left(u_{j}(b) - u^{0}(b)\right)^{2}}{2\sigma^{2}}} \text{ et } P(h_{j}|b) = \frac{P(h_{j})P(b|h_{j})}{\sum\limits_{k \leq m} P(h_{k})P(b|h_{k})}$$

 $ightharpoonup P(h_j)$ updated when an offer b received. Model: weighted sum

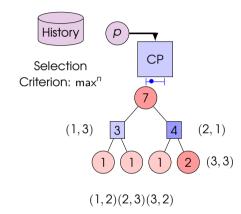
$$u = \sum_{i} P(hj|b) \cdot h_{j}$$

■ effective for numerical a issues, can be easily generalized to categorical

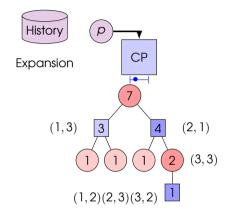




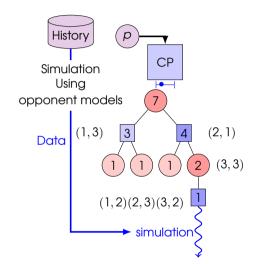


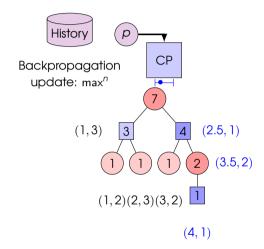














Selection of *j* maximizing [4]:

$$C_{j} = \frac{\bar{X}_{j}}{n_{j}+1} + C \cdot n^{\alpha_{s}} \sqrt{\frac{\ln(n)}{n_{j}+1}}$$

with n total number of simulations, n_j number of times j has been simulated and \bar{X}_i average score of j, C and α_s model parameters.

Expansion of a new node iff [4]

$$n_{D}^{\alpha_{S}} \geqslant n_{C}$$

with n_p number of times the parent has been simulated and n_c number of its children.

Simulation based on opponent models of bidding strategy & utility Backpropagation of the scores; agent & opponent scores



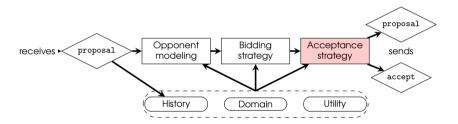
Simulation & backpropagation based on opponent models:

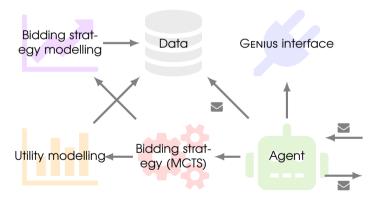
- strategy model (gaussian process regression) [8]
- utility model (apprentissage bayésien) [6]

Pruning

- based on opponent's offers
- delete nodes whose utility is lower than the best opponent proposalsuppression des nœuds dont l'utilité est pire que la meilleure proposition adverse,









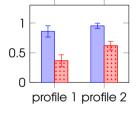
Agents that can negotiate without deadlines:

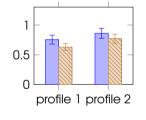
- > RandomWalker [2],
- Tit-for-tat [5],
- Nice Tit-for-tat [2].

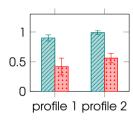
Negotiation domain: ANAC 2014 [7]

- very large (discrete though),
- numerical,
- > nonlinear preferences,
- > set without deadline.









Our agent Random Walker Tit-for-tat 22 Nice Tit-for-tat

Conclusion:

- an agent able to negotiate without predetermined deadline with continuous & categorical issues,
- negotiation strategy based on MCTS, with 2 opponent models and pruning,
- experimental results: outperforms Random Walker & Tit-for-Tat; no significant difference with Nice Tit-for-Tat.

Perspectives:

- customized version to adapt to the context where the deadline is known,
- adapt to the multilateral context,
- use MCTS variations & improvements (AMAF, RAVE...) [3].



Tim Baarslag. "Exploring the Strategy Space of Negotiating Agents: A Framework for Bidding, Learning and Accepting in Automated Negotiation". In: Cham: Springer International Publishing, 2016. Chap. A Component-Based Architecture to Explore the Space of Negotiation Strategie, pp. 53–69.



Tim Baarslag, Koen Hindriks, and Catholijn Jonker. "A Tit for Tat Negotiation Strategy for Real-Time Bilateral Negotiation". In: Complex Automated Negotiations: Theories, Models, and Software Competitions. Ed. by Takayukl Ito et al. Vol. 435. Springer Berlin Heidelberg, 2013, pp. 229–233.



Cameron C Browne et al. "A Survey of Monte Carlo Tree Search Methods". In: IEEE Transactions on Computational Intelligence and Al In Games 4.1 (2012), pp. 1–43.



Adrien Couëtoux. "Monte Carlo Tree Search for Continuous and Stochastic Sequential Decision Making Problems". PhD thesis. Université Paris XI, 2013.



Peyman Faratin, Nicholas R Jennings, and Carles Sierra. "Negotiation decision functions for autonomous agents". In: Robotics and Autonomous Systems 24.3-4 (1998), pp. 159–182.



Koen Hindriks and Dmytro Tykhonov. "Opponent Modelling in Automated Multi-issue Negotiation Using Bayesian Learning". In: Proceedings of the 7th International Joint Conference on Autonomous Agents and Multiagent Systems. Vol. 1. International Foundation for Autonomous Agents and Multiagent Systems, 2008, pp. 331–338.



Raz Lin et al. "Genius: an integrated environment for supporting the design of generic automated negotiators". In: Computational







Colin R Williams et al. "Using Gaussian Processes to Optimise Concession in Complex Negotiations Against Unknown Opponents".

In: Proceedings of the Twenty-Second International Joint Conference on Artificial Intelligence - Volume Volume One. IJCAl'11. AAAI Press, 2011, pp. 432–438.





